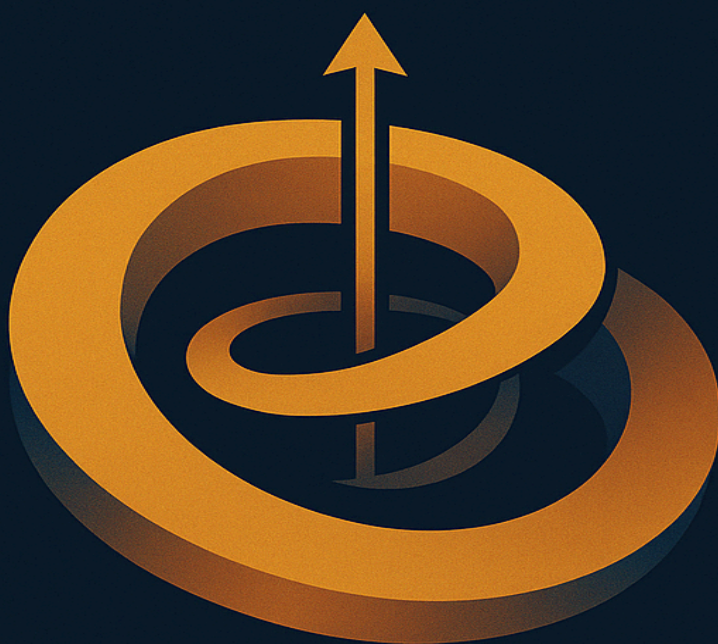


C.U.T. Physics
Coccotunnella Unification Theory

The Hype-Shape Conjecture to CUT-i

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HYPE-SHAPE CONJECTURE

The Hype-Shape, or Eigen-knot, is a geometric structure originating from a torus-like parametrization with a major radius of 10 and a minor radius of 15.85, embedded in a baseline configuration. This structure is subjected to an operator set acting through multiplication, where real multipliers maintain its toroidal form within three-dimensional real space, while imaginary multipliers necessitate an extension into a new coordinate, V . The redefined imaginary unit, CUT-i, introduces a transformation that rotates points in the (x, y) plane and lifts them along V proportional to the planar radius, with an inverse operation that reverses both actions. As a continuous process, it evolves through a flow involving rotation at an angular speed and a V coordinate that increases with planar radius, tempered by damping. Scaling to multiple rings introduces ring-specific parameters and neighbor coupling, leading to diverse banding patterns. The addition of a gravitational term as an opposing pressure allows the structure to self-organize and rise, maintaining stability and helical layering in V , preserving a genus-1 topology while adapting its geometry.

1. The Hype-Shape Conjecture

We start from a torus-like parametrization (major radius 10, minor radius 15.85). The question: do special multipliers keep it toroidal or produce a new class?

$$\text{HypeShape}(\phi, \psi, t) = ((10 + 15.85 \cos \psi) \cos \phi, (10 + 15.85 \cos \psi) \sin \phi, 15.85 \sin \psi)$$

Baseline Hype-Shape embedding.

$$G \sim \{+1, -1, 0, \pm \pi, \pm i, \pm \pi^2, \pm i^2\}$$

Operator set G acting by multiplication on the parametrization.

2. Why this leads to redefining i

Real multipliers live inside R^3 . Multiplying by i does not; it suggests a quarter-turn in a complex plane. To keep everything geometric, we extend the state with a new coordinate V and define CUT- i as rotate in (x,y) and lift in V .

$$i(x, y, z, t, V) = (-y, x, z, t, V + \lambda \sqrt{x^2 + y^2})$$

CUT- i : rotate in (x,y) , lift along V by λ times radius in the plane.

$$i^{-1}(x, y, z, t, V) = (y, -x, z, t, V - \lambda \sqrt{x^2 + y^2})$$

Inverse CUT- i undoes both rotation and lift

$$i^{-1} \circ i = \text{id}$$

Chaining i and i^{-1} yields identity on position; radius in the plane is invariant.

3. Continuous picture

As a flow: rotate at angular speed ω while V increases with planar radius and relaxes with damping μ .

$$\dot{x} = -\omega y, \quad \dot{y} = \omega x, \quad \dot{z} = 0, \quad \dot{V} = \pm k\sqrt{x^2 + y^2} - \mu V$$

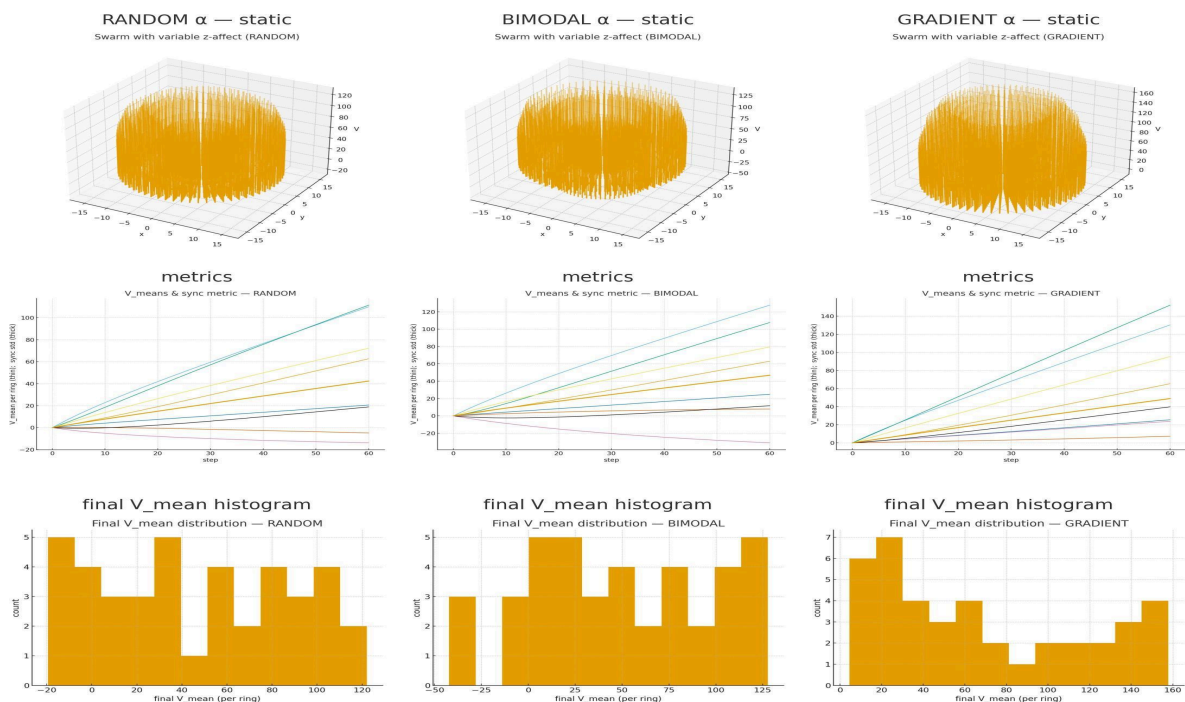
Continuous CUT dynamics (ODE form).

4. From one ring to a swarm

Scale to many rings with ring-specific λ_j , height z_j , and neighbor coupling γ . Apply 90-degree rotation each step, then update V with the rule below.

$$\Delta V_j = \lambda_j \sqrt{x_j^2 + y_j^2} + \alpha_j z_j + \gamma \left(\frac{V_{j-1} + V_{j+1}}{2} - V_j \right)$$

Swarm update: lambda-lift, z-affect, neighbor coupling.



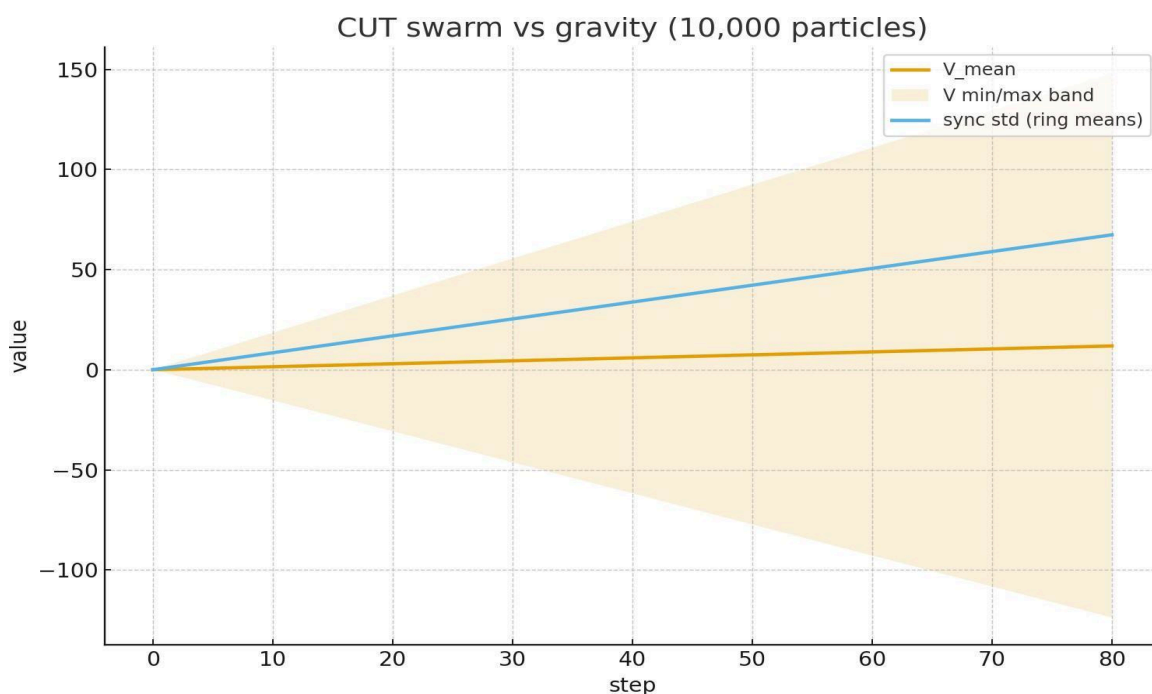
Random, bimodal, and gradient z-affect patterns produce distinct banding.

5. Gravity as i^{-1} pressure

Add a global opposing term g . In brittle models this collapses the system. In CUT-i the swarm self-organizes and keeps rising.

$$\Delta V = (\lambda - g) \sqrt{x^2 + y^2} + \alpha z + \gamma (\bar{V}_{\text{nbr}} - V)$$

Opposing pressure g competes with λ -lift.



10k-particle test: mean V rises; spread stays bounded; synchronization stabilizes.

6. How this ties back to the conjecture

Real multipliers in G keep a torus in \mathbb{R}^3 . Imaginary ones require the V extension. CUT-i yields a quasi-torus helix: topology (genus 1) is preserved while geometry gains helical layering in V .

$$P(\text{Breakoff}) = kV$$

*Optional: breakoff probability knob $P(\text{Breakoff})=k*V$ in the CUT narrative.*

7. What is proved vs. conjectured

Simulations give strong evidence of stability and structure. A formal theorem would require invariants or a proof of class behavior under the CUT-i action.

8. Conclusion

The conjecture forced a geometric meaning for i . Defining CUT-i as rotate-plus-lift ties the hypothesis to concrete behavior: helical banding and resilience under stress. This completes the arc from conjecture to operator to swarm dynamics.

Oscillation Extension.

For oscillatory stability, the CUT-i operator may be alternated with its inverse.

Explicitly: repeat CUT-i, then apply CUT-minus-i (defined as $[-y, x, z, -t, -V + \lambda\sqrt{(x^2 + y^2)}]$).

This cycle prevents collapse and yields a breathing, seesaw-like dynamic consistent with the perception framework first established in *On the Physics of Organic Earth II*.

In this way, oscillation links the Hype-shape conjecture to the CUT-i operator, ensuring the system remains aligned with its original organic rhythm.

4. Pull Operators

4.1 Discrete Pull Operator

The discrete CUT-i pull operator acts by applying a 90° rotation in the (x, y) plane and simultaneously shifting the V -axis by a signed amount proportional to the radius, $r = \sqrt{(x^2 + y^2)}$. Explicitly:

$$\text{CUT-i: } (x, y, z, t, V) \rightarrow (-y, x, z, t, V + \lambda\sqrt{(x^2 + y^2)})$$

$$\text{CUT--i: } (x, y, z, t, V) \rightarrow (y, -x, z, t, V - \lambda\sqrt{(x^2 + y^2)})$$

Here, λ is a coupling parameter that governs the strength of the lift along V . Positive λ produces a lift into H -space, while negative λ produces a descent out of H -space.

4.2 Continuous Pull Field

In the continuous formulation, the pull is represented as a potential function U_H that couples radial extension to displacement along V . The dynamics can be written as:

$$d^2V/dt^2 = -kV + \lambda\sqrt{(x^2 + y^2)}$$

where k is a damping constant. This formulation links planar rotation in (x, y) with the growth or decay of V , producing oscillatory or stabilizing behavior depending on parameter choice.

4.3 Commentary: How This Matches the Narrative

These operators give precise form to the 'push' and 'pull' ideas described in the Hype-Shape Conjecture. In 'On the Physics of Organic Earth II', V was defined as perception. Here it is extended: V is still perception, but also becomes a geometric axis of lift into H -space. The seesaw rhythm is recovered when CUT-i and CUT--i are alternated, generating breathing dynamics.